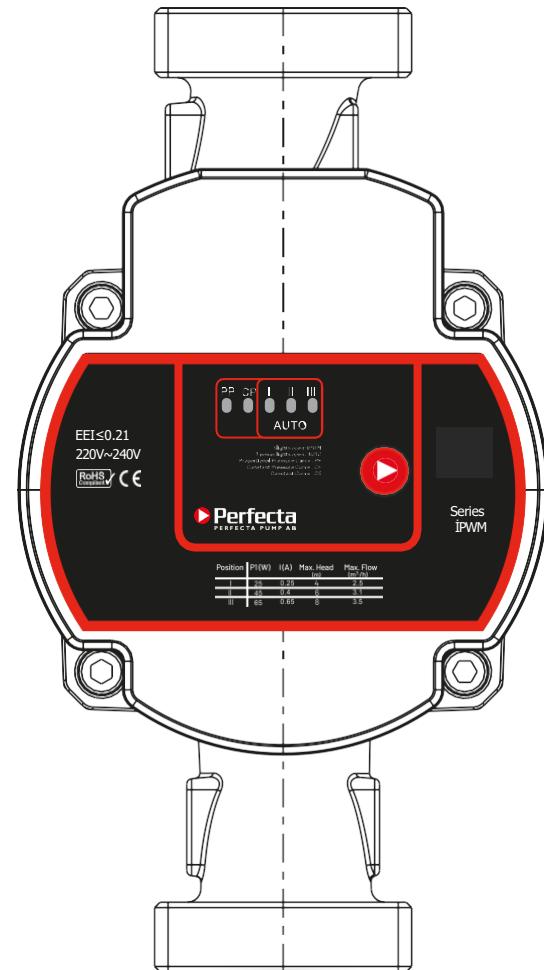




Nemplate Design

- PANTONE 485 C
- BLACK
- PANTONE COLD GRAY 6 C





BOX Design

- PANTONE 485 C
- BLACK
- PANTONE COLD GRAY 6 C



PERFECTA PUMP AB

Perfecta Technical Specification

Application

For domestic hot water system such as mix water under-floor heating system, air energy hot water circulation system, solar hot water circulation system and family hot, cold water pressurization circulation, etc.



Main features

- EEI≤0.21
- Permanent magnet plastic injection motor, intelligent frequency control
- Compact size, easy for installation
- Proportional pressure mode
- Constant pressure mode
- Constant speed mode
- AUTO adapt mode
- PWM external control optional
- Visualized operation
- Low noise, low temperature

Working condition

- Liquid temperature : 2°C ~ 110°C
- Ambient temperature : 0 ~ +40°C
- Max system pressure : 10bar
- Protection level : IP44
- Rated voltage/frequency : 220V ~ 240V/50Hz
- Insulation class : E
- Pumped liquid characteristics: clean liquid, free from solids and mineral oils, non-toxic, chemically neutral, close to the characteristics of water
- Installation: the motor shaft must be kept in horizontal direction



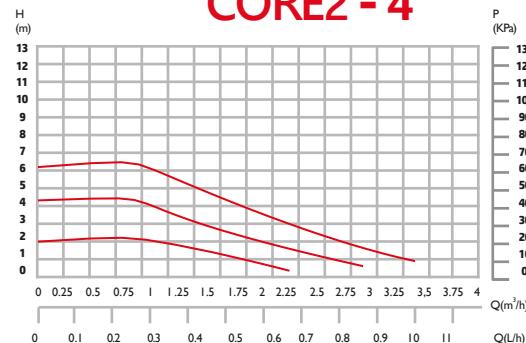
Functions for different model

| Model | Internal control | | | External control |
|-------------------------|------------------|-----|-----|------------------|
| | PP | CP | CS | |
| Core2 XX - X - XXX | I | I | I | PWM1 |
| | II | II | II | |
| | III | III | III | |
| | AUTO | / | / | |
| Core2 XX - X - XXX PWM1 | / | / | III | PWM1 |
| Core2 XX - X - XXX PWM2 | / | / | III | PWM2 |

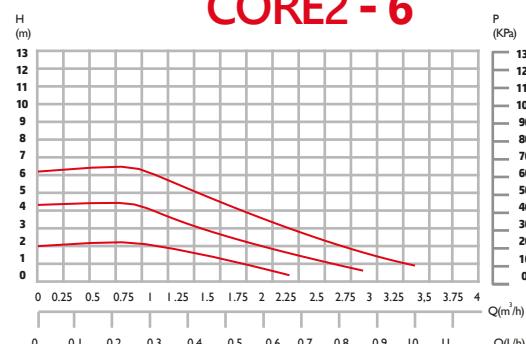
Perfecta

Curve

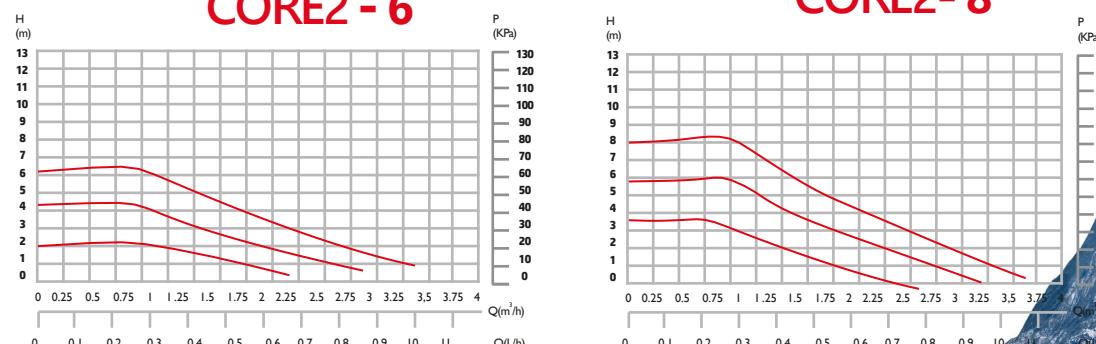
CORE2 - 4



CORE2 - 6



CORE2- 8

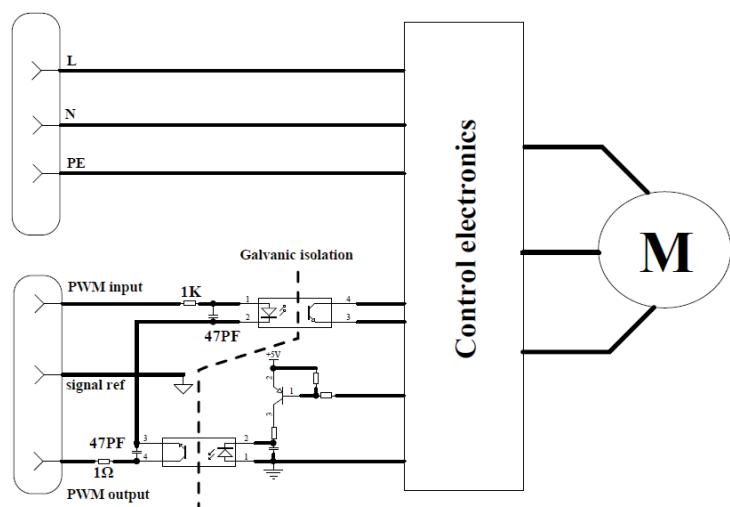


Electrical and hydraulic data

| Model | Inlet/ outlet | | max flow m³/h | Head range m | Voltage V | Frequency Hz | P1 W | In A |
|------------------------------|------------------|------|---------------------|--------------------|--------------|-----------------|---------|---------|
| | mm | | | | | | | |
| Core2 15U-4-130(PWM1/PWM2) | 20 | G1 | 2.2 | 1 ~ 4 | 220 ~ 240 | 50/60 | 25 | 0.3 |
| Core2 25u-4-130(PWM1/PWM2) | 25 | G1.5 | 2.5 | | | | | |
| Core2 25u-4-180(PWM1/PWM2) | 25 | G1.5 | 2.5 | | | | | |
| Core2 32u-4-180(PWM1/PWM2) | 32 | G2 | 2.9 | | | | | |
| Core2 15U-6-130(PWM1/PWM2) | 20 | G1 | 2.9 | 1 ~ 6 | 220 ~ 240 | 50/60 | 40 | 0.5 |
| Core2 25u-6-130(PWM1/PWM2) | 25 | G1.5 | 3.2 | | | | | |
| Core2 25u-6-180(PWM1/PWM2) | 25 | G1.5 | 3.2 | | | | | |
| Core2 32u-6-180(PWM1/PWM2) | 32 | G2 | 3.6 | | | | | |
| Core2 15U-8-130(PWM1/PWM2) | 20 | G1 | 2.9 | 1 ~ 8 | 220 ~ 240 | 50/60 | 65 | 0.65 |
| Core2 25u-8-130(PWM1/PWM2) | 25 | G1.5 | 3.4 | | | | | |
| Core2 25u-8-180(PWM1/PWM2) | 25 | G1.5 | 3.6 | | | | | |
| Core2 32u-8-180(PWM1/PWM2) | 32 | G2 | 4.0 | | | | | |

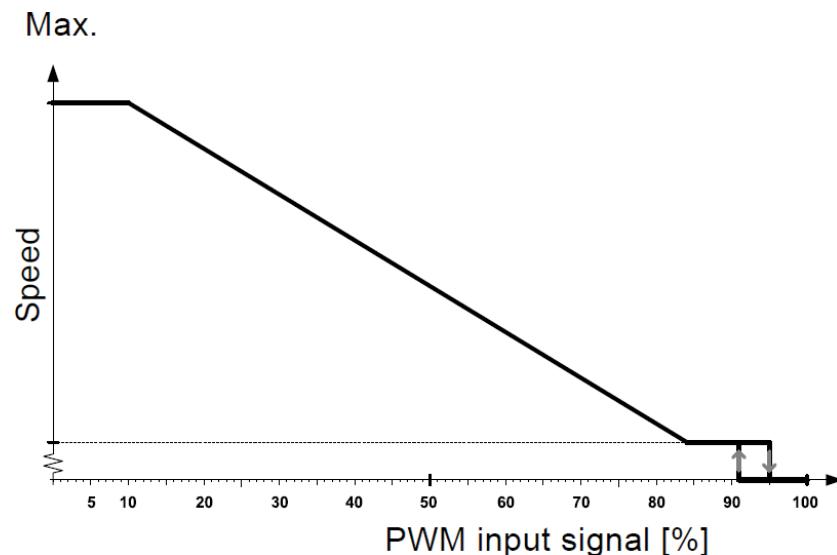
PWM Basic Control Principles

When PWM signal is connected, the operation of circulating pump is controlled by PWM signal. If there is no PWM signal, the operation of circulating pump is controlled by internal control logic.



Pwm Input Signal (P1 Heating)

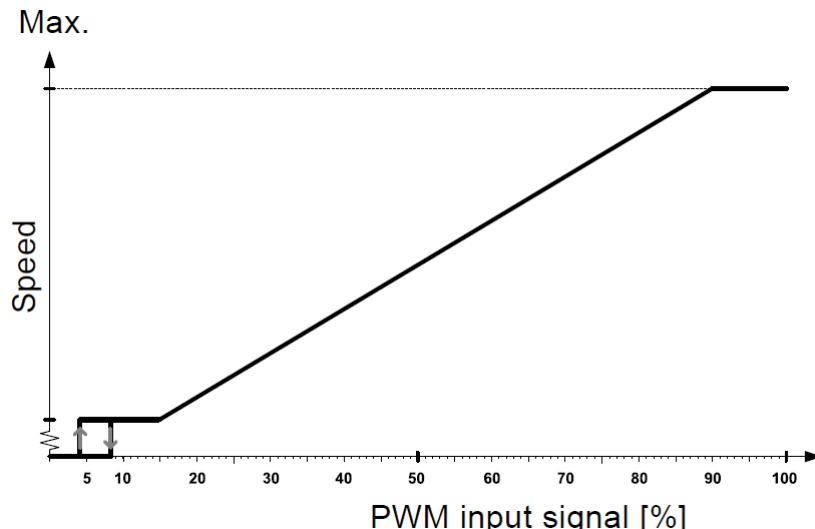
At high PWM signal percentages (duty cycles), a hysteresis prevents the circulating pump from starting and stopping if the input signal fluctuates around the shifting point. At low PWM signal percentages, the circulating pump speed is high for safety reasons. In case of a cable breakage in a gas boiler system, the circulating pump will continue to run at maximum speed to transfer heat from the primary heat exchanger. This is also suitable for heat circulating pumps to ensure that the circulating pump can transfer heat in case of a cable breakage.



| PWM input signal (%) | Pump status |
|----------------------------|--|
| PWM=0 | Switch the pump to non-PWM mode (internal control) operation |
| $0 < \text{PWM} \leq 10$ | Maximum speed: Max. |
| $10 < \text{PWM} \leq 84$ | Variable speed: max. to min. |
| $84 < \text{PWM} \leq 91$ | Minimum speed: Min |
| $91 < \text{PWM} \leq 95$ | Hysteresis area: on/off |
| $95 < \text{PWM} \leq 100$ | Standby mode: off |

Pwm Input Signal (P2 Solar)

At low PWM signal percentages (duty cycles), a hysteresis prevents the circulating pump from starting and stopping if the input signal fluctuates around the shifting point. Without PWM signal percentages, the circulating pump will stop for safety reasons. If a signal missing, for example due to a cable breakage, the circulating pump will stop avoid overheating of the solar thermal system.



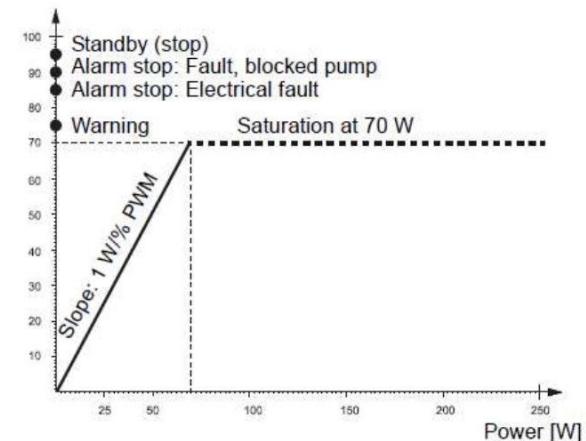
| PWM input signal (%) | Pump status |
|----------------------------|------------------------------|
| PWM=0 | Stop running |
| $0 < \text{PWM} \leq 5$ | Standby mode: off |
| $5 < \text{PWM} \leq 8$ | Hysteresis area: on/off |
| $8 < \text{PWM} \leq 15$ | Minimum speed: Min |
| $15 < \text{PWM} \leq 90$ | Variable speed: min. to max. |
| $90 < \text{PWM} \leq 100$ | Maximum speed: Max. |

Pwm Signal

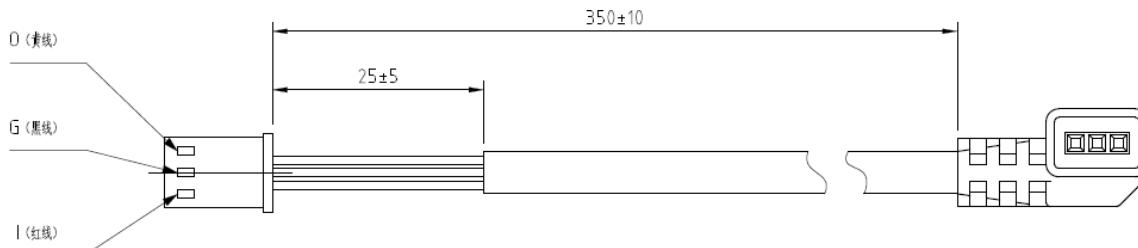
| Optocoupler isolation | | YES |
|------------------------------|-----|--------------------------------------|
| PWM input frequency | | 1000—2500Hz |
| High-level input voltage | UiH | 4.0—5.5V |
| Low-level input voltage | UiL | < 0.7V |
| High-level input current | IH | Max3.5mA@4700Ohms Max10mA@100Ohms |
| PWM output duty cycle | | 0—100% |
| Signal polarity | | fixed |
| Length of signal line | | < 3m |
| Rising and falling edge time | | < T/1000 |

Pwm Feedback Signa (Power Consumption)

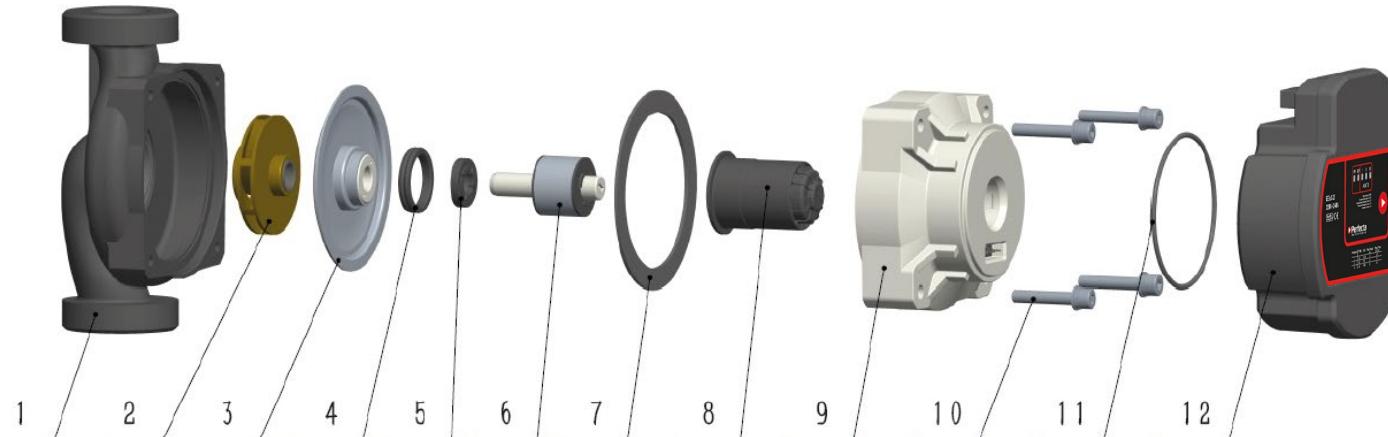
| PWM output signal (%) | Qualification time QT (s) | Pump information | Disqualification time DT (s) | Priority |
|-----------------------|---------------------------|-------------------------------|------------------------------|----------|
| 95 | 0 | Standby by PWM signal (STOP) | 0 | 1 |
| 90 | 30 | Alarm, stop, blocked error | 12 | 2 |
| 85 | 0–30 | Alarm, stop, electrical error | 1–12 | 3 |
| 75 | 0 | Warning | 0 | 5 |
| 0–70 | | 0–70W (slope 1W/%PWM) | | 6 |
| Output frequency | | 75Hz+/-5% | | |



Signal Connection

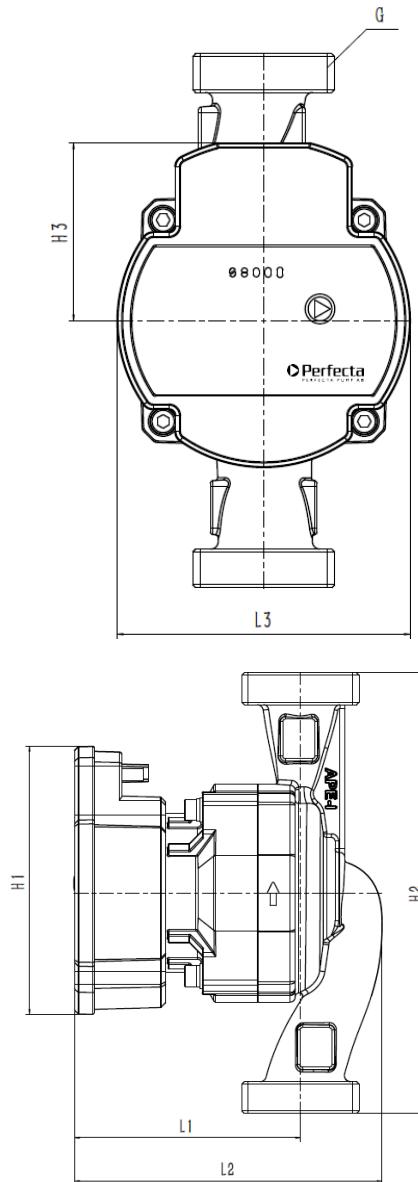


Black: Ground wire (GND)
 Red: PWM input (from controller)
 Yellow: PWM output (from the pump)



| NO | ITEM NAME |
|----|---------------------|
| 1 | Pump body |
| 2 | Impeller |
| 3 | Pump cover assembly |
| 4 | Sealing ring |
| 5 | Thrust bearing |
| 6 | Rotor assembly |

| NO | ITEM NAME |
|----|----------------------|
| 7 | Flat sealing |
| 8 | Rotor can assembly |
| 9 | Motor |
| 10 | Nuts |
| 11 | O-ring |
| 12 | Control box assembly |



| Model CORE2 | Size (mm) | | | | | | | | Inner box (kg) | | Outer box | | | | | | | | | | | | |
|-------------------------|-------------|-----|--------------|-----|------|-----|--------------|--------------|------------------|-----|----------------|-------------|-----------|--|--|--|--|--|--|--|--|--|--|
| | L1 | L2 | L3 | H1 | H2 | H3 | G | Unions | NW | GW | Pcs/ carton | Size (mm) | GW (kg) | | | | | | | | | | |
| 15u-4-130 (PWM1/PWM2) | 93 | 126 | 99 | 110 | 130 | 60 | G1 | G1 to G3/4 | 1.6 | 2.0 | 8 | 310×290×260 | 16 | | | | | | | | | | |
| 15u-6-130 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 15u-8-130 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 25u-4-130 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 25U-6-130 (PWM1/PWM2) | | | | | | | G1 1/2 to G1 | G1 1/2 to G1 | 1.7 | 2.2 | | | | | | | | | | | | | |
| 25U-8-130 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 25U-4-180 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 25U-6-180 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 25U-8-180 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 32U-4-180 (PWM1/PWM2) | 180 | G2 | G2 to G1 1/4 | 2.0 | 2.75 | 2.4 | | | | | | | | | | | | | | | | | |
| 32U-6-180 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |
| 32U-8-180 (PWM1/PWM2) | | | | | | | | | | | | | | | | | | | | | | | |